# **Dylan**Bourgeois

US & French citizen

location NYC. USA birthday 04/11/1994

contact@dtsbourg.me

social @dtsbourg website dtsbourg.me

## can speak...

mother tongue English mother tongue French Spanish fluent

## education

Master of Science & Engineering /speciality Robotics, EPFL

Bachelor of Science & Engineering /speciality Microengineering, EPFL

2012 French Baccalaureate, Scientific specialization summa cum laude

## publications

Explanations and meaningful information: at the interface between technical capabilities and legal frameworks

Bourgeois & Vergnolle PLSC'22

**GNNExplainer:** Generating **Explanations for Graph Neural Networks** 

Ying, Bourgeois, You, Zitnik, Leskovec NeurlPS'19

Selection Bias in News Coverage: Learning It, Fighting It

Bourgeois\*, Rappaz\*, Aberer WWW'18

New approaches for track reconstruction in LHCb's VeLo

Hasse, Albrecht, Couturier, Bourgeois, et al. **THEP'18** 

# experience

@ Ogment.Al, NYC / Lisbon

06/2025 Interim CTO 12/2025

> Led the company pivot from an agentic hiring platform to the best way for companies to create MCPs for their products. Onboarded a dozen pilots, laid the technical and strategy foundation for scaling the company once PMF was achieved.

07/2022 Co-founder, VP of Engineering 06/2025 @ Claryo, San Francisco / NYC Vision - Robotics -World Models

Agents - MCP - SaaS

Provides real-time operational intelligence from visual and events data in logistics warehouses. Creating world models for training and evaluating automation solutions. Raised 12M\$+, company continues to operate.

08/2019 Founding Engineer 10/2022

@ Robust.Al, San Francisco

Vision - Robotics -Factor Graphs

Graph NN - LLMs -

Interpretability

Team lead designing and building an extensible robotics platform that enables reliable behavior for mobile robots equipped with rich sensory input and common sense reasoning. Deployed collaborative robots in 3PL design partner warehouses (e.g. DHL).

09/2018 MSc Thesis 07/2019 @ SNAP, Stanford / LTS2, EPFL

> Designing a new attention-based encoder which learns representations of source code from structure and context. The model can then be fine-tuned to achieve state-of-the-art results on common tasks like naming variables or methods. Also developed and published (NeurIPS'19) state-of-the-art Graph Neural Network explainability methods.

2018 CERN, Geneva 2017 IDIAP, Martigny UPC, Barcelona

Attention Models - Particle Physics Humanoids - Augmented Reality Visual Odometry

## patents

Ultraviolet cleaning trajectory modeling

Trevor, Bourgeois, et al.

**Cleaning Robot** 

R. Brooks, Bourgeois, et al.

Systems & Methods for a Virtual Facility world model

Amer, Bourgeois, et al.

Systems & Methods for a Virtual Facility Supporting Robotics Fleet Control and Sensor Data Simulation

Amer, Bourgeois, et al.

#### Learning Representations of Source Code from Structure & Context

Bourgeois, Catasta, Leskovec

A dynamic embedding model of the media landscape

Rappaz\*, Bourgeois\*, Aberer

Using holistic information in the Trigger

Bourgeois, Fitzpatrick, Stahl LHCb Pub

## can do

## programming

Main ••• Python, TS Scholar ••• C(++) Working Swift, Rust

#### software

PyTorch I Tensorflow I numpy Docker | k8s | GCP | AWS gRPC next.js postgres ROS openCV nerfstudio ISAAC Figma Solidworks XCode

## and also...

**Expert** EPDB on Al

EU Commission, 2022-2025

Venture Partner

Pace Ventures 2025

Advisor Al

Azard, 2025

Blogger Artifices Intelligents, Le Temps Le Temps, 2018-2019

Speaker Al+]ournalism Workshop pilote.media, 2019

Speaker ML Workshop

powercoders, 2018

**Teaching Assistant** 

Applied Data Analysis, EPFL, 2017

Head of IT

Satellite, EPFL, 2016-2017

Stage + Music programmer

Sat Rocks, EPFL, 2016

Code Contributor Signal for iOS

Open Whisper Systems, 2014

Freshman Counselling EPFL, 2014

Teaching Assistant CS101

EPFL, 2013

## and for fun...

Music (curation, DJ) Cooking Climbing Road Biking Tennis

